

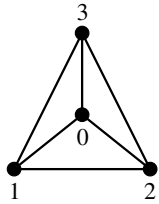
Assignment 2

Ausgabe: 29 Oct 2014 **Abgabe:** 05 Nov 2014

Problem 1: Best-response dynamics

Punkte

Consider the following graph $G = (V, E)$ together with total orderings of all path sets:



$$P^0 : (0)$$

$$P^1 : (1, 2, 0) \succ_1 (1, 0) \succ_1 (1, 3, 0) =_1 (1, 3, 2, 0) =_1 (1, 2, 3, 0) \succ_1 (1)$$

$$P^2 : (2, 3, 0) \succ_2 (2, 0) \succ_2 (2, 1, 0) =_2 (2, 1, 3, 0) =_2 (2, 3, 1, 0) \succ_2 (2)$$

$$P^3 : (3, 1, 0) \succ_3 (3, 0) \succ_3 (3, 2, 0) =_3 (3, 1, 2, 0) =_3 (3, 2, 1, 0) \succ_3 (3)$$

Suppose an initial configuration is

$$\pi(0) = 0, \quad \pi(1) = 2, \quad \pi(2) = 3, \quad \pi(3) = 0.$$

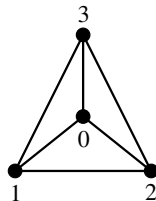
- How many update steps are needed to obtain the same configuration again, if the nodes update their best next hops simultaneously?
- How many update steps are needed by each node on average to obtain the same configuration again, if the nodes update their best next hops sequentially in the order $(1, 2, 3, 1, 2, 3, 1, 2, 3, \dots)$?

Problem 2: Best-response dynamics

Punkte

A configuration π is said to be a fixed-point configuration if and only if $\pi = \pi'$ where π' is the configuration obtained when all nodes simultaneously update their best next hops given π .

Consider again the graph $G = (V, E)$:



If possible, design a total ordering of the path sets P^0, P^1, P^2 , and P^3 such that

- there is a fixed-point configuration π_{fix} and
- there is an initial configuration π_{init} such that π_{fix} is never reached assuming that all nodes updates their best next hops simultaneously.

Problem 3: Valley-free orientations

10 Points

Let $G = (V, E)$ be an undirected graph with vertex set $V = \{0, 1, 2, \dots, n-1\}$. An orientation of an edge $e = \{u, v\}$, $u < v$, in G replaces e by exactly one of the directed edges $u \rightarrow v$ or $u \leftarrow v$. An orientation of G consists of orientations of all edges in G .

(a) Consider the following path set

$$P = \{ (1, 2, 5), (1, 0, 3, 4, 7), (7, 4, 5, 8), (4, 3, 6, 7) \}$$

Find an orientation of the induced graph $G[P]$ such that all paths are valley-free and the oriented graph is acyclic.

- (b) Find a path set P such that an orientation of $G[P]$ cannot satisfy the following both conditions simultaneously:
- i. The oriented graph $G[P]$ is acyclic.
 - ii. All paths in P are valley-free.

Note that, given a path set P , the graph $G[P]$ induced by P consists of all vertices that lie on some path in P and of all edges $\{u, v\}$ such that u and v are neighbored on some path in P .